This paper provides a brief history of computers. It explains basic computer principles and compares computer capabilities. Subjects such as input/output, binary logic, storage, and cost are also discussed. (Author)
DIGITAL COMPUTER PRINCIPLES

J. D. Porter

June 196
ABSTRACT

This paper provides a brief history of computers. It explains basic computer principles and compares computer capabilities. Subjects such as input/output, binary logic, storage, and cost are also discussed.
ACKNOWLEDGMENT

This paper was developed from a series of orientation lectures on computer principles and computer capabilities presented by the author to senior United States Government personnel as a part of the Executive Orientation Program sponsored by The MITRE Corporation jointly with the Electronic Systems Division of the U.S. Air Force Systems Command.
<table>
<thead>
<tr>
<th>Figure No.</th>
<th>Title</th>
<th>Page</th>
</tr>
</thead>
<tbody>
<tr>
<td>1</td>
<td>The Babbage Analytical Machine</td>
<td>1</td>
</tr>
<tr>
<td>2</td>
<td>Analog vs Digital Computation</td>
<td>4</td>
</tr>
<tr>
<td>3</td>
<td>A Human-oriented Data Processing System</td>
<td>7</td>
</tr>
<tr>
<td>4</td>
<td>Notebook Program</td>
<td>8</td>
</tr>
<tr>
<td>5</td>
<td>Computer Block Diagram</td>
<td>10</td>
</tr>
<tr>
<td>6</td>
<td>Input Equipment</td>
<td>11</td>
</tr>
<tr>
<td>7</td>
<td>Bistable Elements</td>
<td>12</td>
</tr>
<tr>
<td>8</td>
<td>Sequence of Bits</td>
<td>13</td>
</tr>
<tr>
<td>9</td>
<td>Binary Counting</td>
<td>14</td>
</tr>
<tr>
<td>10</td>
<td>Binary Notation vs Decimal Notation</td>
<td>15</td>
</tr>
<tr>
<td>11</td>
<td>Fixed and Floating Point Numbers</td>
<td>16</td>
</tr>
<tr>
<td>12</td>
<td>Non-numerical Data</td>
<td>17</td>
</tr>
<tr>
<td>13</td>
<td>Storage Unit</td>
<td>19</td>
</tr>
<tr>
<td>14</td>
<td>Typical Computer Word</td>
<td>20</td>
</tr>
<tr>
<td>15</td>
<td>Control and Arithmetic Units</td>
<td>21</td>
</tr>
<tr>
<td>16</td>
<td>Output</td>
<td>23</td>
</tr>
<tr>
<td>17</td>
<td>Actual Digital Computer</td>
<td>24</td>
</tr>
<tr>
<td>18</td>
<td>Advanced Computer Block Diagram</td>
<td>25</td>
</tr>
<tr>
<td>19</td>
<td>Serial and Parallel Adders</td>
<td>27</td>
</tr>
<tr>
<td>20</td>
<td>Computer Applications</td>
<td>28</td>
</tr>
<tr>
<td>21</td>
<td>Simple Storage Devices</td>
<td>30</td>
</tr>
<tr>
<td>22</td>
<td>Input/Output Devices</td>
<td>32</td>
</tr>
</tbody>
</table>
SECTION I
INTRODUCTION

HISTORY

Man has always striven to develop tools to expand the range of his control, partly to reduce his expenditure of energy but even more to increase his productivity. The abacus was an early tool in the hands of the Chinese merchant to increase the speed and accuracy of the computations needed in the control of his affairs. As early as 1642, Blaise Pascal developed an adding machine employing ratchet-driven number wheels. In 1830, Charles Babbage designed an "Analytical Engine," a section of which is shown in Figure 1, that was designed to sequence automatically through a deck of

Figure 1. The Babbage "Analytical Engine"
prepunched cards carrying out a calculation with no human intervention. The idea of using cards in this way had been devised by Jacquard in France at the end of the seventeenth century to control a loom in weaving complex patterns. However, to make these ideas work required equipment that was far more sophisticated than was available at the time. Even today, our ideas and aspirations for using the equipment keep outstripping the capabilities of the equipment. This distinction between the tools available and how we use them is important to keep in mind. The equipment is often referred to as the hardware and the way we use it (our plans, programs, etc.) is called, by contrast, software.

Computing hardware took its first big step forward in our own electrical age, the twentieth century. The first computing machines were electromechanical. The desk calculator is a good example of such a machine. World War II with its technology explosion, which perhaps the literal explosion of the atomic bomb best symbolizes, called for increased speed in calculating hardware. Scientists met the need with electronic equipment, in which vacuum tubes replaced electromagnetic switches and increased the speed of computers a thousandfold. Vacuum tubes have since been replaced by transistors. Beyond the electronic breakthroughs, probably the single most significant hardware development that made possible today's rapid advances in the application of digital computers was the capability of storing internally to the computer the complete set of instructions and data needed to solve a particular problem. Computers with this capability are called internally stored program computers.

SCOPE OF PAPER

The purpose of this presentation is to convey, to the executive who will use them, a feel for the new computing tools that scientists and engineers have provided him for improved planning and management. I have begun with a
brief historical look at computer development. I shall continue by answering the question, "What is a digital computer?" emphasizing the elements and functions that are common to all computers and describing some of the major differences that are evolving among them.
I have twice used the term digital computer. Two basic computation methods exist, digital and analog. Figure 2 illustrates these.

**DIGITAL COMPUTATION**

The simplest method for computing makes use of a device with which most of us are equipped by nature -- the digits of our hands, whence the name digital computer was derived.

The method involved is one of counting. For example, to add two and three, one can count the corresponding digits of his hands as shown in the figure to obtain the answer five. Similarly, by counting down, one can sub-
tract. Other processes can be built up from this basic one -- for example, multiplication by repetitive addition and differentiation by approximating with small differences.

**ANALOG COMPUTATION**

The second basic method of computation is to make use of a physical process that is similar or analogous to the computation desired. For example, if we place two sticks end-to-end, the length of the combination is the sum of the lengths of each stick. This physical representation is used in the slide rule shown in Figure 2. Capitalizing on the fact that we can multiply two numbers by adding their logarithms, we provide in the slide rule a simple means for multiplying two numbers together. If we represent the logarithms of the numbers as the lengths of two sticks and slide one stick over another, the product will be represented by the sum of the two individual lengths. In much the same manner, electronic analog computers use electrical currents or voltages to represent the quantities to be manipulated.

**ANALOG VERSUS DIGITAL**

Note that in the analog method the results are obtained essentially by a process of measurement. Therefore, the results are limited by the precision of the physical devices involved. Usually this means three- or four-place precision. To obtain greater precision would require rebuilding the device. In contrast, the digital computer allows almost unlimited precision, if we are willing to take the time to carry more digits in our numbers.

There are many problems involving processes, such as differentiation and integration, that are readily handled on an analog device. From an engineer's point of view, the analog computer may permit a closer tie to physical reality. For example, changing a certain potentiometer may be analogous to increasing the wind velocity. On the other hand, there are many problems that are difficult if not impossible to process on an analog computer.
Processes that involve discrete sequences of events and individual items, such as occur in payroll or logistics applications, are more readily handled with digital equipment. There are also installations, called hybrid systems, that combine analog and digital computers. However, the discussions in this presentation will be concerned only with digital computers.
SECTION III
WHAT DOES A COMPUTER DO?

A computer is a data processing system. Data are fed into it; it manipulates the data, perhaps drawing on other data stored within it for the manipulation; it records the results of the manipulation; and finally it puts out the results of its manipulation. Let us for the moment consider the data processing system shown in Figure 3, which is human—rather than machine—oriented.

Figure 3. A Human-oriented Data Processing System

The system in Figure 3 consists basically of an in-basket, an operator, a desk calculator, a notebook, a reference library, and an out-basket. The problem may come to the system in the form of pages to be inserted into the notebook. The operator carries out the procedures described on the notebook pages, transferring numbers from the notebook to the desk calculator,
pushing buttons on the calculator to carry out the required operations, writing intermediate results from the desk calculator back into the notebook, and finally, at appropriate times, arranging the results in the specified form to be delivered as output.

During the calculation the operator may have need to look up certain quantities in tables, such as sine or log tables, stored in his bookcase. This bookcase makes available to the operator large amounts of information, far more than he could store in his notebook. However, when he has to find a quantity in the bookcase, he must interrupt his sequence of computation and spend relatively more time in finding that quantity than he would have if the quantity had been written in his notebook.

If the operator in this system were very naive (as naive, say, as a computer, which has often been characterized as a high-speed moron), a page in his notebook might appear as shown in Figure 4.
Here I have described the steps for adding three numbers together. The numbers have been written on lines 365, 367, and 368. The operator would begin with the instruction on line 375. Note how we would quickly learn to abbreviate the instruction "Add \# from line 366" to "Add 366." It is clear that we do not wish to add 366 but rather the number that has been written on line 366. The operator proceeds sequentially over lines 377 and 378, forming the desired sum and finally writing the answer on line 389. He would then proceed carrying out instructions on lines 380, etc., until finally on line 383 he may be instructed to begin a new manipulation. In Figure 4, if we assume that our numbers have been changed, we might instruct the operator to return to line 375 and repeat the calculation.

In general, then, the system will be provided with the procedures to be followed as a set of instructions and data. Note that each instruction consists essentially of an operation (such as ADD) and an operand (such as "\# from line 396"). After a particular problem has been completed, the system can process a new problem by having a new set of instructions and data placed in the notebook.

Returning to Figure 3, if we desired to speed up the process we might begin by replacing the desk calculator by an electronic device. Even if we could carry out the arithmetic operations in millionths of a second, we would still be limited by the speed at which the instruction and data could be read from the notebook. If we replaced the notebook by an electronic device, we would still be limited by the time required by the human operator to determine which operation was called for by the instruction and to push the appropriate buttons on the desk calculator. If we replaced the desk calculator, notebook, and operator by electronic devices, our overall computation time would still be limited by the time required to transfer the instructions and data to our system and by the time required to transfer the properly formatted results to the customer.
In other words, if we want to speed up this whole process, we must consider mechanizing five basic elements to which we can assign the more functional names of input, output, storage, control, and arithmetic units, as shown in Figure 5.

Figure 5. Computer Block Diagram
SECTION IV
AUTOMATIC DIGITAL COMPUTATION

The discussion in the preceding section accurately portrays the manner in which a computer works, but it drastically oversimplifies the operation. We approach closer to the true complexity of automatic digital computation when we deal with such problems as: What is the internal language of the computer? How are data and instructions stored and manipulated? and, What methods do we have for input and output to and from the machine?

MACHINE INPUT

Figure 6 illustrates some of the many possible inputs to a computer. Where the input is prepared directly by people, the input device may be a tape reader, card reader, keyboard, a set of switches, etc. The input data
may be kept in various forms or media such as paper or magnetic tape, punched cards, magnetic inked characters, and so forth. If the input data is coming from other machines, the input equipment may include analog-to-digital converters. Whatever the input, somewhere in the process the input must be translated into the machine’s own internal language, a language based on binary logic.

**BINARY LOGIC**

The simplest, most reliable way to operate most electronic components

\[
\begin{array}{c|c}
\text{"O" STATE} & \text{"1" STATE} \\
\hline
\text{IBM Punched Card} & 0 \\
\text{Magnetic Core} & \\
\text{Relay or Switch} & \\
\text{Tube or Transistor} & \\
\text{Electrical Pulses} & \\
\end{array}
\]

Figure 7. Bistable Elements

In a simple switch we can have either an on or an off position. In a magnetic core we can have either a clockwise or a counterclockwise polarization. A tube or transistor can be either conducting or not, and so forth. If we think in terms of input to a computer, a hole in a punched card can bring about a conducting state in a switch or transistor, what we call the one (1)
state, and the lack of a hole will cause no action, resulting in a zero (0) state.

Because of this bistable characteristic of computers, all information entered into the machine must be somewhere translated, or coded, perhaps by a keyboard punch or perhaps by a program internal to the machine input unit, into binary notation. The binary notations 1 or 0 are used in various combinations to represent all the quantities in the machine. These notations are binary digits more commonly called bits. By grouping a sequence of these bits as in Figure 8 we form what is known as a word.

Figure 8. Sequence of Bits

We can count just as readily in the binary, or base 2, mode as in the decimal, or base 10, mode.
Figure 9 shows a comparison of numbers from both systems. The decimal system operates with 10 digits, from 0 to 9. To indicate numbers larger than nine, we shift place in the number 10. Place is shifted again at 100, 1,000, and so forth, or in other words at each power of ten. The binary system operates with only two figures, a 1 and a 0; therefore this system is based upon a power of 2, and the progression of the powers of 2 determines the value of any bit position. That is, the place shifts occur at the binary equivalents of 2, 4, 8, 16, 32, and so forth.
That we can represent numbers as readily in the binary system as in the decimal system is shown in Figure 10, where binary notation is on the left and decimal on the right. The binary notation in Figure 10 can also be expressed as follows, reading from left to right: 

\[ (1 \times 2^6) + (1 \times 2^5) + (1 \times 2^4) + (1 \times 2^3) + (1 \times 2^2) + (0 \times 2^1) + (1 \times 2^0) \] or 

\[ (1 \times 64) + (1 \times 32) + (1 \times 16) + (1 \times 8) + (1 \times 4) + (0 \times 2) + (1 \times 1). \]

Figure 10. Binary Notation vs Decimal Notation

To human beings the binary system seems awkward. For a machine, however, able to switch between two stable states at electronic speed, the binary system allows a much simpler design and implementation.

The most common form of data encountered in our early uses of computers was numerical. A number has two basic characteristics, its sign and its magnitude. To handle the sign, we need only allocate one particular bit, usually the first one, with, for example, 1 for plus and 0 for minus. On the other hand, representing the magnitude involves indicating where the binary point is located.
Since all bits look alike, in the early days of computers it was simplest to assume that all numbers were either less than or greater than one. That is, the binary point was assumed to be fixed either at the left end of the number (just after the sign bit) or at the right end. Such numbers are referred to as **fixed-point numbers**. In preparing a problem for solution on a computer, one of the more difficult tasks was keeping track of the binary point. For example, the sum of 10 and 1 is quite different from the sum of 1.0 and 1. This led to the allocation of a set of bits as shown in Figure 11 to indicate that the true location of the binary point is so many places either to the right or left of the indicated position. In the example of Figure 11, the binary point should be moved four places to the left, which can also be shown as an exponent with a power of $-4$. Such numbers are referred to as **floating-point numbers**.

<table>
<thead>
<tr>
<th>SIGN</th>
<th>MAGNITUDE</th>
<th>AS A FIXED-POINT NUMBER</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>0100000001000000000000000100011100000100</td>
<td>+.25195324060</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>SIGN</th>
<th>FRACTION</th>
<th>EXPONENT</th>
</tr>
</thead>
<tbody>
<tr>
<td>0</td>
<td>01000000010000000000000000000000011110000100</td>
<td>2^-4</td>
</tr>
</tbody>
</table>

Figure 11. Fixed and Floating Point Numbers
When computers came to be applied to non-numerical problems, the machine binary language took many forms to satisfy the needs of the data being processed. In Figure 12, I have indicated a few examples of such representations. In the top line of Figure 12, we have a direct representation

<table>
<thead>
<tr>
<th>ALPHABETIC DATA:</th>
</tr>
</thead>
<tbody>
<tr>
<td>B</td>
</tr>
<tr>
<td>110010</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>ALPHAMERIC DATA:</th>
</tr>
</thead>
<tbody>
<tr>
<td>T</td>
</tr>
<tr>
<td>010011</td>
</tr>
</tbody>
</table>

<table>
<thead>
<tr>
<th>PACKED DATA:</th>
</tr>
</thead>
<tbody>
<tr>
<td>EMPLOYEE NO.</td>
</tr>
<tr>
<td>00110101100001</td>
</tr>
</tbody>
</table>

Figure 12. Non-numerical Data
of alphabetic information, the word Boston. With six bits we have 64 distinct configurations (or codes) available. Hence we can arbitrarily associate a unique set of six bits (commonly called a byte) with each of the 26 letters of the alphabet, with the ten decimal digits, and with 28 other special characters such as plus signs, minus signs, equal signs, punctuation marks, and so forth. In the second line of Figure 12, I have portrayed an example of an alphameric entry, that is, an entry that combines both alphabetical and numerical data.

In the third line we have an example of how information can be condensed or "packed" into a word. We can, as in this example, arbitrarily decide that the 15th bit in an entry will represent an employee's sex; thus we need only one bit, a 1 or a 0, to represent either "male" or "female." However, if we wanted to print out the sex of an employee, the computer would first have to determine whether the 15th bit was a 1 or a 0 and then select from a different section of storage a representation of the desired words in the form shown in the first line of Figure 12; that is, after seeing the bit 1, it would select the bytes for "male." The machine would then send the bytes for "male" to an output printer where they would serve as a signal to print the actual sex, "male."

In the foregoing I have briefly summarized the binary system that serves the machine as its internal language. Let us now turn to the machine itself to see how it stores and manipulates its bits and bytes.
The storage unit or memory of a computer can be considered, as shown in Figure 13, to be subdivided into a set of cubby-holes or "cells" (also called memory locations). The contents of each of these cells are a sequence of bits which is called a word. As we have seen, the term byte has been introduced to refer to small groups, usually 6 or 8, of consecutive bits treated as a unit for character representation and other purposes. The size of the word varies among different computers, with 16, 36, 48, and 64 bits being the most common. Note that a cell corresponds to a line in the notebook I discussed earlier in the human-oriented system. Just as we numbered the lines of our notebook, we associate with each cell a number which we call the cell’s address in much the same manner as we identify our homes.

Figure 13. Storage Unit
Also shown in Figure 13 is a switch that is used to select the cell that corresponds to a specified address, allowing the computer to read a word into or out of the selected cell. Designers are expending much effort in the development of techniques that will permit the computer to select a cell on the basis of a logical comparison of the contents of that cell with a specified bit pattern. A storage with this capability is called content-addressed or associative.

In our earlier discussion of a semi-automatic digital computation, we noted that we had to provide our system with a complete set of instructions and data. In the discussion associated with Figures 11 and 12, we have seen how a binary word can be used to represent data. In Figure 14 we can see how a binary word can be used to represent an instruction. As an instruction, it tells the computer what operation is to be performed - for example, add or subtract - and where the number to be operated upon is to be found. In the simplest form, as shown in the figure, only one operand is identified in an instruction. Such a logic is characterized as single-address. In multi-address machines it may be possible to specify two operands, where the answer is to be stored, and/or where the next instruction is to be located. More generally, by allocating the bits in an instruction, one can pack more information into an instruction, such as address modifiers, etc. By allocating more bits for the operation code, a particular machine can offer a wider range of operations.

AS IT APPEARS IN MEMORY:

```
00100000010000000000000011111000
```

AS AN INSTRUCTION:

```
operation: SUB
address: 3972
```

Figure 14. Typical Computer Word
The question of how a word is to be interpreted is decided by the control element, as shown in Figure 15. When the control element takes a word from storage, it treats it as an instruction, separating and decoding the operation portion in order to direct the other elements of the computer system. When the arithmetic unit is directed to select a word from storage (by the address of the operand) it then treats that word as data and operates upon it, as directed by the operation selected. As indicated in Figure 15, the arithmetic unit can carry out a number of operations, both arithmetic and logical. In some computers the arithmetic and control units are considered functionally together and called the processing unit.

As indicated above, to solve a problem the computer must be supplied with a complete set of instructions and data. We call this information a coded program, or more loosely a program. After the program has been read into the computer and stored, the control element is told where to find the first instruction; that is, it is given the address of the first word to be treated as an instruction.
The control element then proceeds sequentially through storage, taking words from successive cells and carrying out instructions until it encounters a so-called jump or transfer of control instruction. Such an instruction may unconditionally cause the control element to go to another section of storage and proceed sequentially from there. Or, the program may call for a conditional transfer depending on a preset option. The computer's power is increased manifold by its ability to transfer to different stored sequences according to preset conditional criteria. To illustrate simply: a computer's program may call for it to multiply two numbers, $x$ times $y$. After the product, $z$, is found it can be compared to another number, $w$. If $z$ is less than $w$, the computer follows one sequence of instructions; if equal, another. The programmer can set up vast numbers of these simple conditions in a long complicated program and thus the computer can carry out very complex decisions at very high speeds. Programmers have used this simple operation to carry out highly sophisticated strategies under dynamic operating conditions. Of course, it is most important that in making these comparisons and selecting the appropriate course of action, the programmer or analyst be aware of the criteria and corresponding courses of action.

**MACHINE OUTPUT**

During the input phase of automatic computation the programmer's language had to be translated into the machine's internal binary language. In the output stage the machine's internal language must be translated back into a language readily understood by the user. Depending upon the user's demands, the output can be quite simple or quite sophisticated. For example, a printout might merely list a series of numbers: 22.42, 36.44, 85.92, etc. However,
if the programmer stores the proper phrases in the computer and calls for
them in the appropriate places in the printout, the list might then read:

John Smith, monthly deductions: $22.42.
Joseph Jones, " $36.44.
Tom Charles, " $85.92.

Many computers have the ability to display their information graphically.
Some of the computer's output abilities are shown in Figure 16. Note that the
forms of the translations may be intended for human interpretation or for use
by other machines, or be a form that can be stored and used a' another time.

![Diagram](image_url)

**Figure 16. Output**

**SUMMARY OF AUTOMATIC DIGITAL COMPUTATION**

To summarize, a digital computer is actually a system, an integrated
set of units. Of course, the modern computer looks far more impressive
when we add the "meat" to the "skeleton" we have been discussing, as shown
Nevertheless, the basic components that we discussed are still recognizable in the figure. As we indicated in Figures 6 and 16, magnetic tapes can be used as either input or output. However, they may also be used to store large amounts of data or special programs in a manner similar to the notebooks that were kept in the bookcase of Figure 3. Such auxiliary or secondary storage is characterized by large capacity and low cost but relatively slow availability. That is, in using such secondary storage the overall computing time may be lengthened. As we will discuss later, other devices such as magnetic disks and drums are also used for secondary storage.

Figure 17. Actual Digital Computer

As time goes on, the basic organization of computers can be expected to change. Some of these changes are part of the natural evolution of computer design logic, such as the overlap of operations, the use of program interrupts for more efficient use of input, output, and auxiliary storage, etc. Some changes are induced by the desire to make more efficient use of computer
elements. For example, a relatively small computer program can tie up the whole computer even though only a relatively small section of storage is used. One way of handling this problem is shown in Figure 18. In this computer organization it is possible to process simultaneously a number of smaller problems, or portions of a larger problem, in the small peripheral computers, permitting them access to the larger central processor and memory as needed.

![Figure 18. Advanced Computer Block Diagram](image-url)
SECTION V
COMPUTER COMPARISONS

As a result of technical development, market requirements, competition, and varied applications, computer makers today offer the user a wide variety of digital computers. At present approximately 60,000 electronic digital computers have been built in the United States, with approximately 25,000 more on order. By 1970 the federal government's annual bill for computing equipment is expected to exceed two billion dollars. In this section I will lay down some general ground rules for comparing computers. My criteria will be cost, application, storage, and input/output equipment.

COST

Perhaps the simplest way to classify computers is by cost. Generally, "You get what you pay for." That you can rent digital computers from a few hundred dollars a month (e.g., PDP-5, Monrobot XI) to a few hundred thousand a month (e.g., CDC 6600) indicates the wide variety available.

Of course, for the higher rentals you get increased speed and computing potential. It is interesting to note that as the price of equipment goes up, the cost per unit of computation goes down. Consequently, in general, it will cost less to do a particular job on a more "expensive" computer. This statement must be qualified by assuming that the job in question pays on a pro rata basis and that the job requires an insignificant amount of manual intervention.

A simple example of the trade-off between cost and processing speed is apparent in the distinction between serial and parallel processing units. For example, as shown in Figure 19, two numbers can be added together a digit at a time. This would involve simply a one-digit adder. One could feed the digits one at a time, taking proper account of carries, storing each resultant digit in the answer. Such a process is obviously much slower than a device that can...
add all of the corresponding digits of the two numbers simultaneously, noting the carries, and then adding in the carries to obtain the sum in basically two steps. This latter process requires a more expensive adder but greatly speeds up the process. Since it operates on all of the digits at the same time (that is, in parallel) it is called a parallel processor in contrast to a serial processor that operates on the digits one at a time. Serial and parallel concepts appear in the machine logic in other areas besides the arithmetic units, such as, for example, in the transmission of words from one location to another. This may be done serially (one bit at a time) or in parallel with a separate transmission path for each bit. In the most modern computers one even finds instructions being executed in parallel (e. g., six at a time in the CDC 6600), in contrast with the basic serial execution of most other computers. In computers, as in Christmas tree lights, parallel circuitry adds to the cost but improves the operational performance manyfold.
Another basic differentiation among computers has been in the type of application, as shown in Figure 20. In the early development of computers, a distinction was made between computers designed for scientific and those for business applications. Scientific problems require large amounts of computation with relatively small amounts of input and output data. On the other hand, business applications involve large amounts of data, relatively small amounts of calculations, with large amounts of output in the form of reports or updated files. Computers were designed for one or the other set of requirements. Even today among our lower and medium-priced computers, this distinction is present. However, in our higher priced, more sophisticated computers, and in new lines of computers now being announced, this distinction is disappearing. These computers combine high-speed processing capability with the ability to process large amounts of input data, and can turn out large amounts of output data.

Real-time application has added yet a third dimension to the way we use computers. "Real-time" is an ill-defined word, in that different computer people mean different things by it. By "real-time," I mean that the results
must be available from the computer in a time consistent with the occurrence of events and with the desired responses. In the previous two classes of applications we were concerned with the amount of information to be processed and with the complexity of the processing. However, scientific and early business requirements placed little restriction on the time required, so that it was not uncommon to allow a computer to grind away overnight carrying out some lengthy calculations (e.g., tables of functions).

However, a number of applications such as teaching systems, process control applications, and guidance and control for various transportation systems require that the computed results be ready within predetermined time limits. The time between events, such as the time required to initiate corrective actions, normally determines these limits.

The availability of computer systems that can respond in real-time has opened up a large area of on-line data processing systems that enter information into the data processor as the data is generated and provide outputs as they are required. Such applications have placed even more difficult requirements on the available storage and input/output devices. Progress in this area has made possible the use of multiple access to the computer, an operation known as time-sharing. In time-sharing, a number of users at remote consoles share the central computer facility. Time-sharing lowers expenses for individual computer users in that it allows them to be on-line to a computer around the clock but to pay only for the computation time they actually use. From the computer installation's point-of-view, the availability of a number of diverse users may make it possible to justify a larger centralized facility and to use that facility more efficiently.

One possible interesting result of this evolution may be a shift in management use of computers away from repetitious printing of compendious...
reports. When a user is limited to batch-processing, that is, when, generally speaking, he must get on the machine and run his entire program or large portions of his program and then get off the machine, he is inclined to want comprehensive printouts in order not to be missing any information that may be needed. In an online situation, if users can learn to trust computers and the accessibility of information in a computer system, perhaps they will come to consider the computer itself a handy repository of essential information which is rapidly accessible when and as needed.

STORAGE

Many materials have been employed in the development of storage devices, but magnetic materials have been used most widely. Figure 21 compares some of the more common storage devices in use today. The table entries must be given as ranges and should be considered only as representative. In the past, disks, drums, and tapes have provided the more common forms of mass storage. Recent developments have extended the capacity of directly addressable core storage, making it available for auxiliary mass storage.

<table>
<thead>
<tr>
<th>STORAGE DEVICE</th>
<th>APPROXIMATE MAXIMUM CAPACITY (MEGABITS)</th>
<th>RANDOM ACCESS TIME (SECONDS)</th>
<th>DATA TRANSFER RATE (MEGABITS/SEC.)</th>
<th>TYPICAL COST (£/BIT)</th>
</tr>
</thead>
<tbody>
<tr>
<td>MAGNETIC CORES</td>
<td>10</td>
<td>0.5 - 8.0 MILLIONTHS</td>
<td>4 - 64</td>
<td>3 - 50</td>
</tr>
<tr>
<td>MAGNETIC DRUM</td>
<td>58</td>
<td>0.02</td>
<td>1.2</td>
<td>0.09 - 0.1</td>
</tr>
<tr>
<td>MAGNETIC DISC</td>
<td>1800</td>
<td>0.15</td>
<td>1.2</td>
<td>0.02 - 0.1</td>
</tr>
<tr>
<td>MAGNETIC TAPE</td>
<td>160</td>
<td>80</td>
<td>0.8</td>
<td>0.01</td>
</tr>
</tbody>
</table>

Figure 21. Sample Storage Devices
The third column in Figure 21 indicates the access time required to place information into or obtain information from the various storage devices. Two situations can be distinguished. The first is called random access and the second sequential access. In random access, the access time is independent of the location of the information most recently obtained from or placed in storage. We often use the term in a relative way, in that access via drum storage is considered less random than access via magnetic cores, but more random than magnetic discs. Magnetic core storage, through a coordinate system, allows the computer to go directly to the core holding the bit of information it wants. Drums and discs involve the positioning of read-write heads and the revolution of drums or discs, and therefore, rather obviously, their access time is not completely independent of the location of the information most recently stored or requested. Magnetic tape, where the computer must search through the contents of a tape in sequence looking for the information it seeks, is at the other end of the access time scale from core storage and is a good example of sequential access.

The third column of Figure 21 lists the random access times for the various magnetic storage devices. Note that the time for magnetic cores is listed in microseconds, the times for the others in seconds. Core memory gives the user a tremendous advantage in access time. However, once you have found your place in memory, the data transfer rates, noted in the fourth column of Figure 21, are quite good for all the devices.

A comparison of the third column with the fifth column, cost, indicates the trade-offs involved. The cost of core memory is many times higher than that of the other methods. Tape memory, with its much slower access time, is also far and away the cheapest method. Of course, several memory devices can be incorporated in one machine. Remember our early, human-oriented example. The notebook represented central storage; the bookcase, bulk
A computer might represent a compromise in that its central storage is handled by core storage and its bulk storage by drum, disc, or tape.

There are many other storage devices available today, including glass delay lines and photographic material as well as other magnetic materials. Also, many other factors must be considered, such as reliability and interconnectability. However, the information presented in Figure 21 should serve as an indication that computing systems can differ significantly just in the choice of storage devices.

INPUT/OUTPUT DEVICES

Figure 22 indicates some of the representative input/output devices available today.
storage. A computer might represent a compromise in that its central storage is handled by core storage and its bulk storage by drum, disc, or tape.

There are many other storage devices available today, including glass delay lines and photographic material as well as other magnetic materials. Also, many other factors must be considered, such as reliability and interconnectability. However, the information presented in Figure 21 should serve as an indication that computing systems can differ significantly just in the choice of storage devices.

**INPUT/OUTPUT DEVICES**

Figure 22 indicates some of the representative input/output devices available today.

![Input/Output Devices](image-url)
As time goes on, old devices are improved and new ones developed. Two of the new input devices not shown in the figure are character-recognition readers and light guns or pencils. The light gun is a device designed to work with a cathode ray tube. With the gun you can point to acceptable words or phrases displayed on the tube and build your own programming statements. Engineers and linguists are currently working on the problem of allowing the user to talk directly to the machine, but the problems in this area are still considerable. In output, however, audible devices are already available, working with an extremely limited set of words and phrases.

As in storage, many trade-offs involving operating characteristics versus cost are involved in input/output devices. As is to be expected, the equipment providing the fastest transfer rates and the more sophisticated responses costs more. Some are very expensive, in some cases costing more than the processing and storage units.
The obvious advantage to computer operation is speed. Increased computing speed provides more timely results, makes possible quick response times, provides the capability of executing, automatically, long, complex sequences of operations, and of processing involved formulae, and makes possible the evaluation of alternative procedures and plans.

Moreover, digital computers have also tremendously increased reliability. Analysts have estimated that a person operating a desk calculator can be expected to make an error on the average of once every thousand operations.

On the other hand, digital computers, particularly the new solid state machines, usually run error-free for many days at a time; in one hour a large computer can perform over a billion operations. Advances in computer technology will continue to improve the reliability of our equipment. Also, reductions in machine down-time increase the equipment availability, in contrast to the availability of the individual worker who loses time because of illness and the ever-decreasing work day.

As we discussed, under storage devices, the digital computer has the ability to store and process large amounts of information. There has been an explosion in the amount of data available in today’s government and industrial systems. With the proliferation of sensor and effector devices, the improvement in communication systems, and the development of new processing requirements, the digital computer has been called upon to provide the data processing capacity needed. Our present-day space program, as an example, would be impossible without computers.

Computers are flexible. The range of problems that a piece of hardware can handle is increased simply by reading a new program into the machine.
Every time a new program has been checked out and added to the machine’s library, a new capability has been added to the machine. For a simple example, once a computer has been programmed to solve standard deviation problems, all the user need do ever after is provide the data and ask the computer to work the standard deviation problem. The computer’s software provides much of the machine’s flexibility, and, as might be expected, is expensive, often as expensive as the hardware itself.

Computers have emancipated mankind from the slavery of performing repetitive, routine calculations by hand. Computers provide a most important tool for assisting man in creative areas such as planning, design, and complex decision making.

Computers can reduce processing costs. In many cases the extent of the savings has been masked by the extension of the computer process to provide new results and services that were not available in the manual system. The use of new storage media associated with the computer processing has resulted in significant savings to many companies in the floor space formerly devoted to data files.

Finally, there is the whole area of improved system performance now available to our system designers. In a sense, it is the realization of the aggregate of the attributes discussed above that has opened new vistas of applications.

We can conclude our discussion by noting that despite exaggerations, disappointments, misuse, and misunderstandings, computers are here to stay. Computers have proved themselves in areas characterized by short response time and routine calculations. For jobs requiring an almost instantaneous processing of large amounts of data, manual systems, no matter how large a manpower effort we may expend, cannot satisfy the requirements. For routine engineering calculations, the cost reduction ratio may be of the order of $10^6$. 
For routine business data processing, such as might be encountered in insurance premium billing, the cost reduction ratio has been found to be on the order of $10^3$ to $10^4$. In language translation, it has been found that computers can just about match a human translator, although in both cases some post-editing may be required. At the moment, in the area of pattern recognition and decision-making we find applications where man is still far ahead of the digital computer.

Obviously, however, we cannot consider the present state of computers as static. As the cost of manpower goes up, and the cost of computers, because of steadily improving hardware and software, goes down, we can expect computers to move into more non-routine areas. Already, computers are encroaching into such areas as bionics, neurophysiology, linguistics, decision theory, and others. The computer age is really only at its beginning.